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On Mathematical Modelling of Metals Distribution in Peat Layers

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Abstract. In this paper we consider averaging and finite difference methods for solving the 3-D boundary-value problem in multilayered domain. We consider the metals Fe and Ca concentration in the layered peat blocks. Using experimental data the mathematical model for calculation of concentration of metals in different points in peat layers is developed. A specific feature of these problems is that it is necessary to solve the 3-D boundary-value problems for elliptic type partial differential equations (PDEs) of second order with piece-wise diffusion coefficients in the layered domain. We develop here a finite-difference method for solving of a problem of one, two and three peat blocks with periodical boundary condition in x direction. This procedure allows to reduce the 3-D problem to a system of 2-D problems by using circulant matrix.

Keywords: 3-D boundary-value problem, averaging method, finite difference method, heavy metals Fe and Ca, peat bog.

AMS Subject Classification: 65N06; 65N08; 34C29; 35R05; 60J60.

1 Introduction

Peat is a mixture of plant remains in different stages of decay consisting in five main groups of organic compounds: proteins, lipids, hydrocarbons, pigments and lignin [11].

Regional climate, the nature of the vegetation, water pH, and degree of metamorphosis may affect the characteristics of the peat [1].

Trace elements accumulated in peat lands have two main natural sources [11]: 1) Atmospheric deposition of soil dusts and aerosols; 2) The incorporation as particulate matter or in solution via runoff and ground waters (by mineral dissolution or desorption of compounds previously accumulated in the environment). Main anthropogenic pollution sources are atmospheric particles, waste waters, results of changes in environmental conditions such as changes in pH value [11]. Although at trace levels some heavy metals are essential for plants and animals, at higher concentrations they become dangerous for any form of life [10].

Mathematical models which based on real measurements (which were made more easily accessible locations, for example, on the earth surface, or between layers of peat and with the minimum required number of measurements) are more reasonable to use for practical estimation of necessary elements of other required points of peat layers.

The task of sufficient accuracy numerical simulation of quickly solution 3-D problems for mathematical physics in multilayered media is important in known areas of the applied sciences. To achieve this goal we consider two methods: special finite difference scheme and averaging method with integral parabolic splines. For engineering calculation the concentration of metal in peat layered block the averaging method is chosen. The finite-difference method is used only for solving the obtained 2-D problems.

A. Buikis ([4], [5] 1994) consider different assumptions for averaging methods along the vertical coordinate. These methods were applied for the mathematical simulation of the mass transfer process in multilayered underground systems. It is necessity to solve the 3-D initial-boundary-value problems for parabolic type partial differential equations of second order with piece-wise parameters in multilayer domain. The special spline, which interpolated middle integral values of piece-wise smooth function, is defined. With the help of this spline is reduce the 3-D problem of mathematical physics with piece-wise coefficients to 2-D problems for system of equations.

A. Buikis and H. Kalis averaged the hydrodynamical functions (velocity, stream function, temperature) in the z-direction by mathematical simulation of an electrolytic cell for aluminum production (two layers). For the viscous incompressible liquid the system of Navier-Stokes equations is considered in layered media. The equations are averaged along the height of the layers and square-law approximation of functions along z-coordinate is used [3]. The system of averaged 2-D equations is discretized on general irregular meshes and special monotone finite-difference schemes are used [8].

H. Kalis ([9] 1997) developed an effective finite-difference method for solving a problem of the above type. This method may be considered as a generalization of the method of finite volumes [12] for layered systems. This procedure allows to reduce the 3-D problem to a system of 2-D problem and 2-D problems to a system of 1-D problems. The approximation is based on the conservation law approach.

A. Buikis and H. Kalis ([6] 2001) discussed the problem of radiative heating of thin plate based on the finite volume and conservative averaging methods. The aim of this paper is to verify exactness of the averaging method applied to the heat transfer with nonlinear Stefan-Boltzmann boundary conditions. The method of conservative averaging (AV method) is compared with the finite volumes method (FV). These methods allow for reduction of the nonlinear 2-D heat transport problem, described by a partial differential equation, to an initial value problem stated as a system of two nonlinear ordinary differential equations (ODEs) of the first order in the time or to an initial-value problem as a system of one such equation of the first order and two nonlinear algebraic equations.

The solution of the stiff systems of ODEs have be obtained using MAPLE routines. The approximate values of temperature found by FV and AV methods are compared with values of the analytical method obtained by the Laplace transform.

M. Buike and A. Buikis ([2] 2007) investigated the approximation error of the interpolation by integral parabolic spline S(x) for the function U(x), $x \in [a, b]$ itself, its first and second derivatives (here is assumed, that second and third derivatives of the function are piece-wise continuous).

They have following estimate:

$$|U^p(x) - S^p(x)| \le C_p \alpha_N \|\tilde{\Delta}_N\|^{2-p}, \quad p = 0, 1, 2,$$

where $\alpha_N = \omega(U'', \|\tilde{\Delta}_N\|)$, Here ω is the continuity modulus for second derivatives U'' of interpolation function U on the grid $\tilde{\Delta}_N$: $\omega(U, \delta) = \max |U(x + h) - U(x)|, |h| \le \delta, x, x + h \in [a, b].$

2 A Mathematical Model

The process of diffusion the metal in the peat block is consider in 3-D parallelepiped

$$\Omega = \{ (x, y, z) : 0 \le x \le l, \ 0 \le y \le L, \ 0 \le z \le Z \}.$$

The domain Ω consist of multilayer medium. We will consider the stationary 3-D problem of the linear diffusion theory for multilayered piece-wise homogeneous materials of N layers in the form

$$\Omega_i = \{ (x, y, z) : x \in (0, l), \ y \in (0, L), \ z \in (z_{i-1}, z_i) \}, \quad i = \overline{1, N},$$

where $H_i = z_i - z_{i-1}$ is the height of layer Ω_i , $z_0 = 0$, $z_N = Z$. We will find the distribution of concentrations $c_i = c_i(x, y, z)$ in every layer Ω_i at the point $(x, y, z) \in \Omega_i$ by solving the following partial differential equation (PDE):

$$D_{ix}\partial^2 c_i/\partial x^2 + D_{iy}\partial^2 c_i/\partial y^2 + D_{iz}\partial^2 c_i/\partial z^2 + f_i(x, y, z) = 0, \qquad (2.1)$$

where D_{ix} , D_{iy} , D_{iz} , are constant diffusion coefficients, $c_i = c_i(x, y, z)$ – the concentrations functions in every layer, $f_i(x, y, z)$ – the fixed sours function.

The values c_i and the flux functions $D_{iz}\partial c_i/\partial z$ must be continues on the contact lines between the layers $z = z_i$, $i = \overline{1, N-1}$:

$$c_i|_{z_i} = c_{i+1}|_{z_i},$$

$$D_{iz}\partial c_i/\partial z|_{z_i} = D_{(i+1)z}\partial c_{i+1}/\partial z|_{z_i},$$
(2.2)

where $i = \overline{1, N - 1}$.

We assume that the layered material is bounded above and below with the plane surfaces z = 0, z = Z with fixed boundary conditions in following form:

$$D_{1z}\frac{\partial c_1(x,y,0)}{\partial z} - \alpha \left(c_1(x,y,0) - C_0(x,y)\right) = 0, \quad c_N(x,y,Z) = C_a(x,y), \quad (2.3)$$

where C_0 , C_a are given concentration-functions, α is the mass transfer coefficient. We have two form of fixed boundary conditions in the x, y directions:

1) the periodical conditions by x = 0, x = l in the form

$$c_i(0, y, z) = c_i(l, y, z), \quad \partial c_i(0, y, z) / \partial x = \partial c_i(l, y, z) / \partial x,$$

2) the symmetrical conditions by y = 0, y = L

$$\partial c_i(x,0,z)/\partial y = \partial c_i(x,L,z)/\partial y = 0.$$

For solving the problem (2.1)–(2.3) we will consider conservative averaging (AV) and finite difference (FD) methods. These procedures allow to reduce the 3-D problem to 2D boundary value problem for the system of partial differential equations with circulant matrix in the x-directions.

The AV-Method with Quadratic Splines 3

The equation of (2.1) are averaged along the heights H_i of the layers Ω_i and quadratic integral splines along z coordinate in following form one used [2,4,7]

$$c_i(x, y, z) = C_i(x, y) + m_i(x, y)(z - \overline{z_i}) + e_i(x, y)G_i((z - \overline{z_i})^2 / H_i^2 - 1/12), \quad (3.1)$$

where $G_i = H_i/D_{iz}$, $\overline{z_i} = (z_{i-1} + z_i)/2$, $z \in [z_{i-1}, z_i]$, m_i , e_i , C_i are the unknown coefficients of the spline-function, $C_i(x,y) = H_i^{-1} \int_{z_i}^{z_i} c_i(x,y,z) dz$ are the average values of c_i , $i = \overline{1, N}$.

After averaging the system (2.1) along every layer Ω_i , we obtain N system of 2-D PDE

$$D_{ix}\partial^2 C_i/\partial x^2 + D_{iy}\partial^2 C_i/\partial y^2 + 2H_i^{-1}e_i + F_i(x,y) = 0, \qquad (3.2)$$

where $F_i = H_i^{-1} \int_{z_{i-1}}^{z_i} f_i(x, y, z) dz$ are the average values of f_i , $i = \overline{1, N}$.

From boundary conditions (2.3) follows

$$\frac{6}{\alpha}(D_{1z}m_1 - e_1) + 3m_1H_1 = 6(C_1 - C_0) + e_1G_1,$$

$$3m_NH_N = 6(C_a - C_N) - e_NG_N.$$
(3.3)

From (2.2) follows

$$3H_im_i + e_iG_i = 6(C_{i+1} - C_i) - 3H_{i+1}m_{i+1} + e_{i+1}G_{i+1},$$

$$D_{iz}m_i + e_i = D_{(i+1)z}m_{i+1} - e_{i+1}, \quad i = \overline{1, N - 1}.$$
(3.4)

572 I. Kangro, H. Kalis, A. Gedroics, E. Teirumnieka and E. Teirumnieks Excluding m_{i+1} from (3.4) we get

$$3m_i D_{iz}(G_i + G_{i+1}) + e_i(G_i + 3G_{i+1}) + 2e_{i+1}G_{i+1} = 6(C_{i+1} - C_i), \quad i = \overline{1, N-1}.$$
(3.5)

Replacing i with i-1 and then excluding m_{i-1} we obtain

$$3m_i D_{iz}(G_i + G_{i-1}) - e_i(G_i + 3G_{i-1}) - 2e_{i-1}G_{i-1} = 6(C_i - C_{i-1}), \quad i = \overline{2, N}.$$
(3.6)

For determined e_i we exclude m_i from (3.5), (3.6)

$$2e_{i-1}G_{i-1}(G_i + G_{i+1}) + e_i((G_i + 3G_{i-1})(G_i + G_{i+1}) + (G_i + 3G_{i+1})(G_i + G_{i-1})) + 2e_{i+1}G_{i+1}(G_i + G_{i-1}) = 6(C_{i+1} - C_i)(G_i + G_{i-1}) - 6(C_i - C_{i-1})(G_i + G_{i+1}), \quad i = \overline{2, N-1}.$$
(3.7)

From (3.5), (3.6) by i = 1, i = N follows

$$3m_1D_{1z}(G_1 + G_2) + e_1(G_1 + 3G_2) + 2e_2G_2 = 6(C_2 - C_1),$$
(3.8)
$$3m_ND_{Nz}(G_N + G_{N-1}) - e_N(G_N + 3G_{N-1}) - 2e_{N-1}G_{N-1} = 6(C_N - C_{N-1}).$$

Excluding from (3.6), (3.8) m_1 , m_N we obtain equations for e_1 , e_N

$$e_{1}\left[2G_{1}+4G_{2}+\frac{2}{\alpha}\left(4+\frac{6G_{2}}{G_{1}}\right)\right]+2e_{2}\left(G_{2}+\frac{2G_{2}}{\alpha G_{1}}\right)$$
$$=6(C_{2}-C_{1})\left(1-\frac{2}{\alpha G_{1}}\right)-6(C_{1}-C_{0})\left(1+\frac{G_{2}}{G_{1}}\right),$$
$$e_{N}(2G_{N}+4G_{N-1})+2e_{N-1}G_{N-1}$$
$$=-6(C_{N}-C_{N-1})+6(C_{a}-C_{N})\left(1+\frac{G_{N-1}}{G_{N}}\right).$$
(3.9)

The system of algebraic equations (3.7), (3.9) can be solved by Thomas algorithm for tri-diagonal matrix [12]. From (3.3), (3.6) we obtain m_i , $i = \overline{1, N}$:

$$m_{i} = \frac{G_{i}}{3H_{i}(G_{i} + G_{i-1})} \left(e_{i}(G_{i} + 3G_{i-1}) + 2e_{i-1}G_{i-1} + 6(C_{i} - C_{i-1}) \right], \ i = \overline{2, N},$$

$$m_{1} = \frac{1}{3H_{1} + 6D_{1z}/\alpha} \left[6(C_{1} - C_{0}) + e_{1}(G_{1} + 6/\alpha) \right].$$
(3.10)

3.1 The AV-method for 3, 2 and 1 layers

In the case N = 3 (three layers) we have equations (3.9) and (3.7) for i = 2. Then

$$e_i = e_{i,1}C_1 + e_{i,2}C_2 + e_{i,3}C_3 + e_{i,0},$$

$$m_i = m_{i,1}C_1 + m_{i,2}C_2 + m_{i,3}C_3 + m_{i,0}, \quad i = 1; 2; 3,$$
(3.11)

where

$$e_{2,1} = \left(6(G_2 + G_3) + b_1 k_{1,1} (2 + k_{2,1} + \alpha_1) \right) / d,$$

$$\begin{split} e_{2,2} &= -\left(6(2G_2+G_3+G_1)+b_1k_{1,1}(1+\alpha_1)+b_3k_{2,2} \right)/d, \\ e_{2,3} &= \left(6(G_2+G_1)+b_3k_{2,2}(2+k_{2,3}) \right)/d, \qquad \alpha_1 = \frac{2}{\alpha G_1}, \\ e_{2,0} &= -(b_1k_{1,1}(1+k_{2,1}C_0+b_3k_{2,2}(1+k_{2,3}C_a))/d, \qquad d = a_1+a_2+a_3, \\ a_2 &= (G_2+3G_3)(G_2+G_1)+(G_2+G_3)(G_2+3G_1), \qquad a_1 = -a_{2,1}b_1, \\ a_3 &= -a_{2,3}b_3, \qquad b_1 = 2G_1(G_2+G_3), \qquad b_3 = 2G_3(G_2+G_1), \\ a_{2,1} &= \frac{G_2+2k_{2,1}/\alpha}{G_1+2G_2+alf}, \qquad a_{2,3} = k_{2,3}/(1+2k_{2,3}), \qquad k_{2,1} = G_2/G_1, \\ k_{2,3} &= G_2/G_3, \qquad k_{1,1} = 3/(G_1+2G_2+alf), \qquad k_{2,2} = 3/(G_3+2G_2), \\ alf &= (4+6k_{2,1})/\alpha, \qquad e_{1,1} = -a_{2,1}e_{2,1} - k_{1,1}(2+k_{2,1}+\alpha_1), \\ e_{1,2} &= -a_{2,1}e_{2,2} + k_{1,1}(1+\alpha_1), \qquad e_{1,3} = -a_{2,3}e_{2,1}, \\ e_{3,2} &= -a_{2,3}e_{2,2} + k_{2,2}, \qquad e_{3,3} = -a_{2,3}e_{2,3} - k_{2,2}(2+k_{2,3}), \\ e_{3,0} &= -a_{2,3}e_{2,0} + k_{2,2}(1+k_{2,3})Ca, \\ m_{1,1} &= -(g_{1,2}e_{1,1}+g_{3,2}e_{2,1}+6)/d_1, \qquad m_{1,2} = -(g_{1,2}e_{1,2}+g_{3,2}e_{2,2}-6)/d_1, \\ m_{1,3} &= -(g_{1,2}e_{1,3}+g_{3,2}e_{2,3})/d_1, \qquad m_{1,0} = -(g_{1,2}e_{1,0}+g_{3,2}e_{2,0})/d_1, \\ d_1 &= 3(1+k_{2,1})H_1, \qquad g_{1,2} &= G_1+3G_2, \qquad g_{3,2} &= 2G_2, \\ m_{3,1} &= (g_{3,3}e_{3,1}+g_{3,2}e_{2,1})/d_3, \\ m_{3,0} &= (g_{3,3}e_{3,0}+g_{3,2}e_{2,0})/d_3, \qquad d_3 &= 3(1+k_{2,3})H_3, \qquad g_{3,3} &= G_3+3G_2, \\ m_{2,1} &= (g_{2,2}e_{2,1}+g_{2,1}e_{1,1}-6)/d_2, \qquad m_{2,2} &= (g_{2,2}e_{2,2}+g_{2,1}e_{1,2}+6)/d_2, \\ m_{2,3} &= (g_{2,2}e_{2,3}+g_{2,1}e_{1,3})/d_2, \qquad m_{2,0} &= (g_{2,2}e_{2,0}+g_{2,1}e_{1,0})/d_2, \\ d_2 &= 3H_2(1+k_{2,1})/k_{2,1}, \qquad g_{2,2} &= G_2+3G_1, \qquad g_{2,1} &= 2G_1, \end{aligned}$$

We can obtain that $e_{1,2} = e_{2,1}$, $e_{1,3} = e_{3,1}$, $e_{3,2} = e_{2,3}$, $e_{1,2} = e_{2,1}$, and the matrix of the 3. order with the elements $e_{i,j}$ is symmetric and $e_{1,1} < 0$, $e_{2,2} < 0$, $e_{3,3} < 0$.

From (3.2), (3.11) follows the system of three PDE

$$\begin{cases} D_{1x}\partial^2 C_1(x,y)/\partial x^2 + D_{1y}\partial^2 C_1(x,y)/\partial y^2 + 2H_1^{-1}e_1(x,y) + \tilde{F}_1(x,y) = 0, \\ D_{2x}\partial^2 C_2(x,y)/\partial x^2 + D_{2y}\partial^2 C_2(x,y)/\partial y^2 + 2H_2^{-1}e_2(x,y) + \tilde{F}_2(x,y) = 0, \\ D_{3x}\partial^2 C_3(x,y)/\partial x^2 + D_{3y}\partial^2 C_3(x,y)/\partial y^2 + 2H_3^{-1}e_3(x,y) + \tilde{F}_3(x,y) = 0, \end{cases}$$
(3.12)

where $\tilde{F}_i(x, y) = F_i(x, y) + 2H_1^{-1}e_{i,0}, i = 1; 2; 3.$

In the case N = 2 (two layers) we have coefficients from (3.11) i = 1; 2

$$\begin{aligned} e_{1,1} &= -\left(a_{2,1}k_{2,2} + k_{1,1}(2 + k_{2,1} + \alpha_1)\right)/d, \\ e_{1,2} &= \left(a_{2,1}k_{2,3} + k_{1,1}(1 + \alpha_1)\right)/d, \\ e_{1,0} &= \left(-a_{2,1}k_{2,4}C_a + k_{1,1}(1 + k_{2,1})C_0\right)/d, \qquad k_{2,2} = 3/(G_2 + 2G_1), \\ k_{2,3} &= k_{2,2}(2 + k_{1,2}), \qquad k_{2,4} = k_{2,2}(1 + k_{1,2}), \qquad d = 1 - a_{1,3}, \\ a_{1,3} &= a_{2,1}a_{2,3}, \qquad a_{2,3} = 1/(2 + k_{2,1}), \qquad e_{2,1} = (-a_{2,3}e_{1,1} + k_{2,2}), \end{aligned}$$

$$\begin{split} e_{2,2} &= -a_{2,3}e_{1,2} - k_{2,3}, \qquad e_{2,0} = -a_{2,3}e_{1,0} - k_{2,4}C_a, \\ m_{1,1} &= (g_{1,1}e_{1,1} + 6)/d_1, \qquad m_{1,2} = g_{1,1}e_{1,2}/d_1, \\ m_{1,0} &= (g_{1,1}e_{1,0} - 6C_0)/d_1, \qquad d_1 = 3H_1 + 6D_{1z}/\alpha, \qquad m_{2,1} = -G_2e_{2,1}/d_2, \\ m_{2,2} &= -(G_2e_{2,1} + 6)/d_2, \qquad m_{2,0} = (-G_2e_{2,0} + 6C_a)/d_2, \qquad d_2 = 3H_2. \end{split}$$

From (3.12) follows the system of two PDE.

In the case N = 1 (one layer) we have coefficients from (3.11) i = 1

$$\begin{split} e_{1,1} &= -a_{1,1}(2G_1 + 2/\alpha), \quad e_{1,0} = a_{1,1} \left(G_1 C_0 + (G_1 + 2/\alpha) C_a \right), \\ a_{1,1} &= \frac{3}{G_1 (G_1 + 4/\alpha)}, \quad m_{1,1} = -(G_1 e_{1,1} + 6)/d, \\ m_{1,0} &= -(G_1 e_{1,0} - 6C_a)/d, \quad d = 3G_1. \end{split}$$

From (3.12) one PDE follows.

4 The Finite Difference Method

For solving 2-D problems we consider an uniform grid $(N_x \times (N_y + 1))$: $\omega_h = \{(x_i, y_j), x_i = ih_x, y_j = (j - 1)h_y, i = \overline{1, N_x}, j = \overline{1, N_y + 1}, N_x h_x = l, N_y h_y = L\}$. Subscripts (i, j) refer to x, y indices, the mesh spacing in the x_i, y_j directions are h_x and h_y .

We can the PDEs (3.12) rewritten in following vector form:

$$D_x \partial^2 C / \partial x^2 + D_y \partial^2 C / \partial y^2 - AC + \tilde{F} = 0, \qquad (4.1)$$

where D_x , D_y are the 3 order diagonal matrices with elements D_{1x} , D_{2x} , D_{3x} and D_{1y} , D_{2y} , D_{3y} , C is the 3 order vectors-column with elements C_1 , C_2 , C_3 , \tilde{F} is also the vectors-column with elements \tilde{F}_1 , \tilde{F}_2 , \tilde{F}_3 , and A is the block matrix in following form:

$$A = -2 \begin{pmatrix} e_{1,1}/H_1 & e_{1,2}/H_1 & e_{1,3}/H_1 \\ e_{2,1}/H_2 & e_{2,2}/H_2 & e_{2,3}/H_2 \\ e_{3,1}/H_3 & e_{3,2}/H_3 & e_{3,3}/H_3 \end{pmatrix}.$$

The matrix A has positive eigenvalues and the system (4.1) is correctly focused.

For 2 and 1 layer we have the matrix with 2 and 1 blocks.

The equation (4.1) with periodical conditions for vector function C in the uniform grid (x_i, y_j) is replaced by vector difference equations of second order approximation:

$$AA W_{j-1} - CC W_j + BB W_{j+1} + \bar{F}_j = 0, \qquad (4.2)$$

where W_j , \bar{F}_j , $j = \overline{2, N_y}$ are the $M \times N$, $(M = N_x)$ order vectors-column with elements $C_{k,i,j} \approx C_k(x_i, y_j)$, $\bar{F}_{k,i,j} = \tilde{F}_k(x_i, y_j)$, $i = \overline{1, M}$, k = 1; 2; 3, AA, CC, BB = AA are the 3 block-matrices of M order circulant symmetric matrix [13]. The circulant matrix can to give with the first rows and the calculation (matrix inversion and multiplication) can be carried out with MATLAB using simple formulae for obtaining the first M elements of matrix. The boundary conditions are replaced by difference equations of first order approximation:

$$C(x, h_y) = C(x, 0) + O(h_y), \qquad C(x, L) = C(x, L - h_y) + O(h_y).$$

The vectors-column W_j from (4.2) is calculated by Thomas algorithm [12] in the matrix form using MATLAB.

$$W_j = X_j W_{j+1} + Y_j = 0, \quad j = N_y(-1)1,$$
(4.3)

where X_j , Y_j are corresponding matrices and vectors, obtaining of following expressions

$$X_j = (CC_j - AA_j X_{j-1})^{-1} BB_j, (4.4)$$

$$Y_j = (CC_j - AA_j X_{j-1})^{-1} (AA_j Y_j + F_j), \quad j = 2(1)N_y.$$
(4.5)

Here $X_1 = E$, $Y_1 = 0$, $W_{\bar{N}+1} = (E - X_{\bar{N}})^{-1}Y_{\bar{N}}$, $(\bar{N} = N_y)$ where E is unit matrix.

Solving 3D problems in comparing with the standard FDS methods we use circulant matrices in one direction thus the periodical boundary conditions are approximated. This allows saving CPU time by using Thomas algorithm. However, analytical modifications become more complicated in the case of 3layers due to the calculations with 3rd order block-matrices, which elements are circulant matrices. But in the case of N > 3 the algorithm's building become more complicated. To perform calculations in the case of multiple layers (N > 3) being based on the following approach is complicate. Then it is better to use well-known finite difference techniques with alternating direction methods, by reducing 3D problems on 1D due to iterative procedures.

5 Approbation of Numerical Algorithms

We consider following test for the approbation of the calculations: $f_1 = f_2 = f_3 = C_0 = 0$, $\alpha = 6D_{1z}$; $600D_{1z}$. $C_a = C_0 \cos(\pi y/L)\sin(2\pi x/l)$, $C_0 = 1$.

5.1 Three layers

The special solutions in the form $c_i(x, y, z) = g_i(z) \cos(\pi y/L) \sin(2\pi x/l)$, i = 1; 2; 3 of the PDE (2.1) can be obtain from following boundary value problem for three ODE (for conditions (2.2), (2.3));

$$g_1''(z) - a_1^2 g_1(z) = 0, \quad D_{1z} g_1'(0) - \alpha (g_1(0) - C_0) = 0,$$

$$g_2''(z) - a_2^2 g_2(z) = 0, \quad g_3''(z) - a_3^2 g_3(z) = 0,$$

$$g_3(Z) = C 0_a, \quad g_1(H_1) = g_2(H_1), \quad D_{1z} g_1'(H_1) = D_{2z} g_2'(H_1),$$

$$g_2(L_1) = g_3(L_1), \quad D_{2z} g_2'(L_1) = D_{3z} g_3'(L_1), \quad (5.1)$$

where $L_1 = H_1 + H_2$, $a_i = \pi \sqrt{\left(\frac{4D_{ix}}{l^2} + \frac{D_{iy}}{L^2}\right)/D_{iz}}$, i = 1; 2; 3.

	$\alpha = 600$	$\alpha = 600$	$\alpha = 6$	$\alpha = 6$
z_k	c_{ap}	c_{an}	c_{ap}	c_{an}
0.00	.0020	.0021	.1206	.1257
0.25	.0328	.0339	.1395	.1451
0.50	.0642	.0659	.1599	.1659
0.75	.0963	.0986	.1820	.1883
1.00	.1292	.1321	.2057	.2123
1.25	.1476	.1508	.2196	.2264
1.50	.1671	.1705	.2350	.2420
1.75	.1877	.1912	.2521	.2591
2.00	.2096	.2133	.2709	.2780
2.25	.2331	.2367	.2917	.2986
2.50	.2578	.2617	.3142	.3213
2.75	.6189	.6272	.6469	.6568

Table 1. The analytical and numerical results for 3 layers (max. and min. values \pm).

Therefore the exact solution is

 $g_1(z) = P_1 \sinh(a_1 z) + P_0 \cosh(a_1 z), \quad g_2(z) = P_2 \sinh(a_2 z) + P_3 \cosh(a_2 z),$ $g_3(z) = P_4 \sinh(a_3 z) + P_5 \cosh(a_3 z),$

where the constants $\overline{P_0, P_5}$ are calculated from (5.1).

The averaged values are

$$\begin{aligned} H_1^{-1} \int_0^{H_1} g_1(z) dz &= \frac{1}{H_1 a_1} \left(P_1 \left(\cosh(a_1 H_1) - 1 \right) + P_0 \sinh(a_1 H_1) \right), \\ H_2^{-1} \int_{H_1}^{L_1} g_2(z) dz &= \frac{1}{H_2 a_2} \left(P_3 \left(\sinh(a_2 L_1) - \sinh(a_2 H_1) \right) \right. \\ &+ P_2 \left(\cosh(a_2 L_1) - \cosh(a_2 H_1) \right) \right), \\ H_3^{-1} \int_{L_1}^Z g_3(z) dz &= \frac{1}{H_3 a_3} \left(P_5 \left(\sinh(a_3 Z) - \sinh(a_3 L_1) \right) \right. \\ &+ P_4 \left(\cosh(a_3 Z) - \cosh(a_3 L_1) \right) \right). \end{aligned}$$

We have the following numerical results $(H_1 = 1, H_2 = 1.5, H_3 = 0.5, Z = 3.0, C_0 = 0, C_0 = 1)$ for maximal and minimal values of c_k in the plane $z = z_k$, $z_k = (k-1)h_z$, $k = \overline{1, 12}$, $z_{13} = Z$, $z_5 = H_1$, $z_{11} = H_1 + H_2$, $h_z = 0.25$ by:

$$D_{1z} = 10^{-3}, \ D_{2z} = 1.875 \ 10^{-3}, \ D_{3z} = 0.1333 \ 10^{-3}, \ \alpha = 600 D_{1z}, \ \alpha = 6D_{1z},$$

$$D_{1x} = D_{1y} = 310^{-4}, \quad D_{2x} = D_{2y} = 410^{-4}, \quad D_{3x} = D_{3y} = 510^{-5}.$$

The numerical results by $N_x = N_y = 20$, $N_z = 12$ is given in Table 1 (c_{ap} , c_{an} are the approximate and analytical-exact values. We have the following averaged (integral) values:

1) $\alpha = 600D_{1z}$ - for C_{ap} : $C_1 = 0.0646$, $C_2 = 0.1894$, $C_3 = 0.6202$; for C_{an} : $C_1 = 0.0663$, $C_2 = 0.1931$, $C_3 = 0.6284$;

2) $\alpha = 6D_{1z}$ - for C_{ap} : $C_1 = 0.1609$, $C_2 = 0.2545$, $C_3 = 0.6482$; for C_{an} : $C_1 = 0.1669$, $C_2 = 0.2617$, $C_3 = 0.6581$.

The numerical results for $N_x = N_y = 40$ are coincided with 3 decimal places.

5.2 Two layers

The special solutions in the form $c_i(x, y, z) = g_i(z) \cos(\pi y/L) \sin(2\pi x/l)$, i = 1; 2 of the PDE (2.1) can be obtain from following boundary value problem for two ODE (for conditions (2.2), (2.3)):

$$g_1''(z) - a_1^2 g_1(z) = 0, \qquad D_{1z} g_1'(0) - \alpha (g_1(0) - C_0) = 0, g_2''(z) - a_2^2 g_2(z) = 0, \qquad g_2(Z) = C 0_a, g_1(H_1) = g_2(H_1), \qquad D_{1z} g_1'(H_1) = D_{2z} g_2'(H_1),$$
(5.2)

where $Z = H_1 + H_2$, $a_i = \pi \sqrt{\left(\frac{4D_{ix}}{l^2} + \frac{D_{iy}}{L^2}\right)/D_{iz}}$, i = 1; 2. Therefore the exact solution is

$$g_1(z) = P_1 \sinh(a_1 z) + P_0 \cosh(a_1 z), \qquad g_2(z) = P_2 \sinh(a_2 z) + P_3 \cosh(a_2 z),$$

where the constants $\overline{P_0, P_3}$ are calculated from (5.2).

The averaged values are

$$H_1^{-1} \int_0^{H_1} g_1(z) dz = \frac{1}{H_1 a_1} \left(P_1 \left(\cosh(a_1 H_1) - 1 \right) + P_0 \sinh(a_1 H_1) \right),$$

$$H_2^{-1} \int_{H_1}^{L_1} g_2(z) dz = \frac{1}{H_2 a_2} \left(P_3 \left(\sinh(a_2 L_1) - \sinh(a_2 H_1) \right) + P_2 \left(\cosh(a_2 L_1) - \cosh(a_2 H_1) \right) \right).$$

We have following numerical results $(H_1 = 1, H_2 = 2, Z = 3.0, C_0 = 0, C_0 = 1)$ for maximal and minimal values of c_k in the plane $z = z_k, z_k = (k-1)h_z, k = \overline{1,12}, z_{13} = Z, z_5 = H_1, z_{11} = 2.5, h_z = 0.25$ by:

$$D_{1z} = 10^{-3}, \ D_{2z} = 1.875 \ 10^{-3}, \ \alpha = 600 D_{1z}, \ \alpha = 6 D_{1z},$$

 $D_{1x} = D_{1y} = 310^{-4}, \ D_{2x} = D_{2y} = 310^{-4}.$

The numerical results are given in Table 2. We have following averaged (integral) values:

- 1) $\alpha = 600D_{1z}$ for C_{ap} : $C_1 = 0.2092$, $C_2 = 0.6832$; for C_{an} : $C_1 = 0.2160$, $C_2 = 0.6970$;
- 2) $\alpha = 6D_{1z}$ for C_{ap} : $C_1 = 0.4481$, $C_2 = 0.7585$; for C_{an} : $C_1 = 0.4647$, $C_2 = 0.7752$.

5.3 One layer

The special solutions in the form $c_1(x, y, z) = g_1(z) \cos(\pi y/L) \sin(2\pi x/l)$, 2 of the PDE (2.1) can be obtain in the following form:

	$\alpha = 600$	$\alpha = 600$	$\alpha = 6$	$\alpha = 6$
z_k	c_{ap}	c_{an}	c_{ap}	c_{an}
0.00	.0067	.0069	.3374	.3498
0.25	.1072	.1103	.3898	.4039
0.50	.2086	.2147	.4457	.4618
0.75	.3115	.3211	.5064	.5240
1.00	.4172	.4304	.5718	.5911
1.25	.4759	.4909	.6099	.6297
1.50	.5382	.5537	.6519	.6715
1.75	.6041	.6193	.6979	.7165
2.00	.6736	.6879	.7479	.7651
2.25	.7468	.7599	.8020	.8175
2.50	.8267	.8357	.8632	.8739
2.75	.9111	.9156	.9292	.9347

Table 2. The analytical and numerical results for 2 layers (max. and min. values \pm).

$$g_1''(z) - a_1^2 g_1(z) = 0, \qquad D_{1z} g_1'(0) - \alpha \left(g_1(0) - C_0\right) = 0, \qquad g_1(Z) = C 0_a,$$

where $a_1 = \pi \sqrt{\left(\frac{4D_{1x}}{l^2} + \frac{D_{1y}}{L^2}\right)/D_{1z}}.$

Therefore the exact solution is

$$g_1(z) = P_1 \sinh(a_1 z) + P_0 \cosh(a_1 z),$$

where the constants

$$P_1 = \frac{C0_a - C_0 \cosh(a_1 Z)}{\sinh(a_1 Z) + z_1 a_1 \cosh(a_1 Z)}, \qquad P_0 = z_1 a_1 P_1 + C_0.$$

The averaged values are

$$H_1^{-1} \int_0^{H_1} g_1(z) dz = \frac{1}{H_1 a_1} \left(P_1 \left(\cosh(a_1 H_1) - 1 \right) + P_0 \sinh(a_1 H_1) \right).$$

We have following numerical results $(H_1 = Z = 3.0, C_0 = 0, C0_a = 1)$ for maximal and minimal values of c_k in the plane $z = z_k, z_k = (k-1)h_z, k = \overline{1, 12}, z_{13} = Z, z_5 = 1, z_{11} = 2.5, h_z = 0.25$ by:

$$D_{1z} = 10^{-3}, \quad \alpha = 600 D_{1z}, \quad \alpha = 6 D_{1z}, \quad D_{1x} = D_{1y} = 310^{-4}.$$

The numerical results are given in Table 3. We have following averaged (integral) values:

1)
$$\alpha = 600D_{1z}$$
 - for C_{ap} : $C_1 = 0.4435$; for C_{an} : $C_1 = 0.4530$;

2) $\alpha = 6D_{1z}$ - for C_{ap} : $C_1 = 0.5398$; for C_{an} : $C_1 = 0.5646$.

6 Determining the Diffusion Coefficient in the 1D Case

After recording the diffusion coefficient in one layer and solving linear 1D problem it is possible to calculate other diffusion coefficients using experimental measurements in the contact lines between the layers.

	$\alpha = 600$	$\alpha = 600$	$\alpha = 6$	$\alpha = 6$
z_k	c_{ap}	c_{an}	c_{ap}	c_{an}
0.00	.0037	.0045	.2178	.2518
0.25	.0618	.0714	.2531	.2908
0.50	.1242	.1390	.2937	.3325
0.75	.1910	.2079	.3395	.3773
1.00	.2621	.2787	.3905	.4256
1.25	.3376	.3521	.4468	.4778
1.50	.4174	.4288	.5083	.5344
1.75	.5016	.5094	.5751	.5960
2.00	.5901	.5948	.6486	.6631
2.25	.6853	.6857	.7280	.7363
2.50	.7853	.7829	.8131	.8164
2.75	.8902	.8873	.9038	.9040

Table 3. The analytical and numerical results for 1 layer (max. and min. values \pm).

6.1 Three layers

In 1D case we have the boundary value problem of the following 3 ODEs

$$c_1''(z) = 0, \quad c_2''(z) = 0, \quad c_3''(z) = 0,$$

$$D_{1z}c_1'(0) - \alpha(c_1(0) - C_0) = 0, \quad c_3(Z) = C0_a,$$

$$c_1(H_1) = c_2(H_1), \quad D_{1z}c_1'(H_1) = D_{2z}c_2'(H_1),$$

$$c_2(L_1) = c_3(L_1), \quad D_{2z}c_2'(L_1) = D_{3z}c_3'(L_1).$$
(6.1)

Using relations $D_{1z}/D_{2z} = x1$, $D_{1z}/D_{3z} = y1$, $D_{1z}/\alpha = z1$ we have following solutions:

$$c_1(z) = C_1 z + C_2, \quad c_2(z) = C_3 z + C_4, \quad c_3(z) = C_5 z + C_6,$$
 (6.2)

where $C_1 = \frac{C0_a - C_0}{H_1 + x1H_2 + y1H_3 + z_1}$, $C_2 = C_0 + z1C_1$, $C_3 = x1C_1$, $C_4 = C0_a - C_1(L_1x1 + y1H_3)$, $C_5 = y1C_1$, $C_6 = C0_a - C_1y1Z$.

From experimentally obtained data $c_1(0) = C00, c_1(H_1) = C01, c_2(L_1) = C02$, we can determined the relations

$$x1 = \frac{H_1(C02 - C01)}{H_2(C01 - C00)}, \quad y1 = \frac{H_1(Ca - C02)}{H_3(C01 - C00)}, \quad z1 = \frac{H_1(C00 - C_0)}{(C01 - C00)}.$$

We consider the data for 2 metals in the peat blocks with $H_1 = 1$, $H_2 = 1.5$, $H_3 = 0.5$:

- 1) for Fe: $C0_a = 1.88$, $C_0 = 0$, C00 = 0.66, C01 = 0.83, C02 = 1.50 we get $D_{2z} = 0.38D_{1z}$, $D_{3z} = 0.22D_{1z}$, $\alpha = 0.26D_{1z}$,
- 2) for Ca: $C0_a = 4.63$, $C_0 = 0$, C00 = 1.30, C01 = 1.90, C02 = 2.38 we get $D_{2z} = 1.875 D_{1z}$, $D_{3z} = 0.133 D_{1z}$, $\alpha = 0.46 D_{1z}$.

We obtain with MAPLE by $D_{1z} = 10^{-3}$ Figs. 1, 2 and the coefficients C_1 , C_2 , C_3 , C_4 , C_5 , C_6 depending on C00, C01, C02.

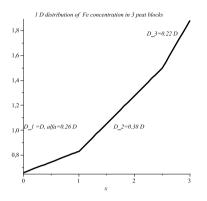


Figure 1. Fe distribution and D_z .

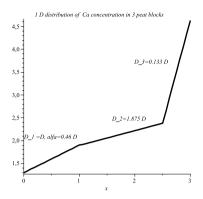


Figure 2. Ca distribution and D_z .

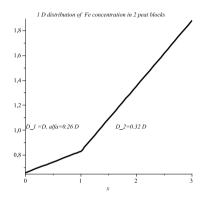


Figure 3. Fe distribution and D_z .

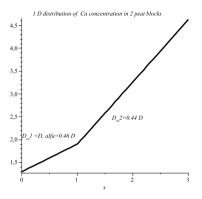


Figure 4. Ca distribution and D_z .

6.2 Two layers

For two layers $H_1 = 1$, $H_2 = 2$, Z = 3 solution of ODEs (6.1) is

$$c_1(z) = C_1 z + C_2, \quad c_2(z) = C_3 z + C_4,$$
(6.3)

where $C_1 = \frac{C0_a - C_0}{H_1 + x1H_2}$, $C_2 = C_0 + z1C_1$, $C_3 = x1C_1$, $C_4 = C0_a - C_1Zx1$. From $c_1(0) = C00$, $c_1(H_1) = C01$ follows

$$x1 = \frac{H_1(C0_a - C01)}{H_2(C01 - C00)}, \qquad z1 = \frac{H_1(C00 - C_0)}{(C01 - C00)}$$

In this case for Fe $-D_{2z} = 0.32D_{1z}$, $\alpha = 0.26D_{1z}$, and for Ca- $D_{2z} = 0.44D_{1z}$, $\alpha = 0.46D_{1z}$. We obtain $D_{1z} = 10^{-3}$ in Figs. 3, 4.

6.3 One layer

For one layer $H_1 = Z = 3$ solution of ODEs (6.1) is $c_1(z) = C_1 z + C_2$, where $C_1 = \frac{C0_a - C_0}{H_1 + z_1}$, $C_2 = C_0 + z_1 C_1$. From $c_1(0) = C_0$ follows

$$z1 = \frac{H1(C00 - C_0)}{(C0_a - C00)}$$

In this case $(D_{1z} = 10^{-3})$ for Fe $-\alpha = 0.62D_{1z}$, and for Ca- $\alpha = 0.85D_{1z}$.

7 Some Numerical Results

We consider the metals **Fe** and **Ca** concentration in the 3, 2 and 1 layered peat blocks Ω (see Fig. 3) with L = l = 1m, Z = 3. L = l = 1m, $Z = H_1 + H_2 + H_3 = 3m$, $H_1 = 1m$, $H_2 = 1.5m$, $H_3 = 0.5m$.

On the top of earth (z = Z) are measure the concentration $c\frac{mg}{kg}$ of metals in following nine points in the (x, y) plane:

1) for Fe:

c(0.1, 0.2) = 1.69, c(0.5, 0.2) = 1.83, c(0.9, 0.2) = 1.72, c(0.1, 0.5) = 1.70, c(0.5, 0.5) = 1.88, c(0.9, 0.5) = 1.71, c(0.1, 0.8) = 1.71, c(0.5, 0.8) = 1.82, c(0.9, 0.8) = 1.73,

2) for Ca:

c(0.1, 0.2) = 3.69, c(0.5, 0.2) = 4.43, c(0.9, 0.2) = 3.72, c(0.1, 0.5) = 4.00, c(0.5, 0.5) = 4.63, c(0.9, 0.5) = 4.11, c(0.1, 0.8) = 3.71, c(0.5, 0.8) = 4.50, c(0.9, 0.8) = 3.73.

This date are smoothing in matrix C_a by 2D interpolation with MATLAB operator, using the spline function. In Figs. 7–8 we can see the distribution of concentration c for Fe and for Ca in the (x, y) plane by z = Z.

We have examining the convergence and accuracy by reducing the mesh spacing in the direction of the x, y twice. The vector difference equations (4.2) were solved repeatedly, reducing step h_x and and h_y twice and the results obtained, which coincides with 2 decimal places.

7.1 3 layers

For 3 layers we use $Z = H_1 + H_2 + H_3 = 3m$, $L_1 = H_1 + H_2 = 2.5$, $H_1 = 1m$, $H_2 = 1.5m$, $H_3 = 0.5m$ and following diffusion coefficients in the layers:

- 1) for Fe (C00 = 0.66, $C0_a = 1.88$): $D_{1z} = 10^{-3}, D_{2z} = 0.38 * 10^{-3}, D_{3z} = 0.22 * 10^{-3},$
- 2) for Ca (C00 = 1.30, $C0_a = 4.63$): $D_{1z} = 10^{-3}$, $D_{2z} = 1.875 * 10^{-3}$, $D_{3z} = 0.1333 * 10^{-3}$.

The diffusion coefficients in x, y directions are

$$D_{1x} = D_{1y} = 310^{-4}, \qquad D_{2x} = D_{2y} = 410^{-4}, \qquad D_{3x} = D_{3y} = 510^{-5}.$$

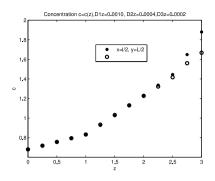


Figure 5. c depending on z for Fe in 3-layers.

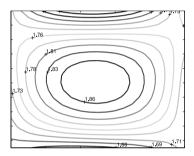


Figure 7. Levels of c by z = Z for Fe.

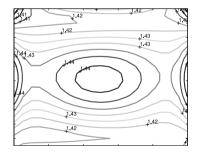


Figure 9. Levels of c by $z = H_1 + H_2$ for Fe in 3-layers.

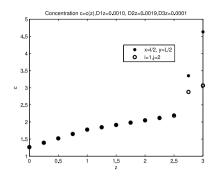


Figure 6. c depending on z for Ca in 3-layers.

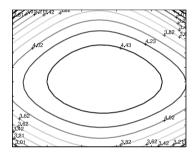


Figure 8. Levels of c by z = Z for Ca.

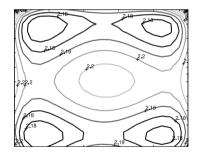


Figure 10. Levels of c by $z = H_1 + H_2$ for Ca in 3-layers.

In Figs. 5, 6 are the graphics of metals concentration c depending on vertical coordinate z by x = l/2, y = L/2 and in other points. In Figs. 9–12 we can see the distribution of concentration c for Fe and for Ca in the different (x, y) plane by $z = H_1 + H_2$, z = 0. For the peat block corresponding experimental

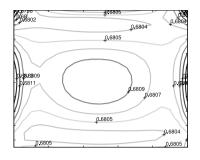


Figure 11. Levels of c by z = 0 for Fe in 3-layers.

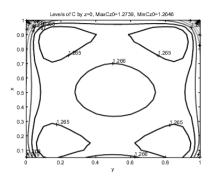


Figure 12. Levels of c by z = 0 for Ca in 3-layers.

Table 4. The experimental and numerical results by x = 0.5m, y = 0.5m depending on z.

z $c_{num} - Fe$ $c_{exp} - Fe$ $c_{num} - Ca$ $c_{exp} - C$	a
0.000 0.681 0.660 1.267 1.300	
0.250 0.719 1.395	
0.500 0.756 1.522	
0.750 0.793 1.649	
1.000 0.829 0.830 1.780 1.900	
$1.250 0.926 \qquad \qquad 1.844$	
1.500 1.025 1.914	
1.750 1.127 1.150 1.985 1.980	
2.000 1.231 2.057	
2.250 1.337 2.132	
2.500 1.4458 1.500 2.207 2.380	
2.750 1.649 3.351	
3.000 1.880 1.880 4.630 4.630	

 (c_{exp}) and numerical (c_{num}) results by x = 0.5m, y = 0.5m depending on z are obtained in Table 4.

7.2 2 layers

For 2 layers we use $Z = H_1 + H_2 = 3m$, $H_1 = 1m$, $H_2 = 2m$ and following diffusion coefficients in the layers:

- 1) for Fe $D_{1z} = 10^{-3}$, $D_{2z} = 0.38 * 10^{-3}$,
- 2) for Ca $D_{1z} = 10^{-3}$, $D_{2z} = 1.875 * 10^{-3}$.

The diffusion coefficients in x, y directions are $D_{1x} = D_{1y} = 310^{-4}$, $D_{2x} = D_{2y} = 410^{-4}$.

In Figs. 13, 14 are the graphics of metals concentration c depending on vertical coordinate z by x = l/2, y = L/2 and in other point. In Figs. 15–18 we can see the distribution of concentration c for Fe and for Ca in the (x, y) plane by z = 0, z = 2.5. For the peat block corresponding experimental (c_{exp})

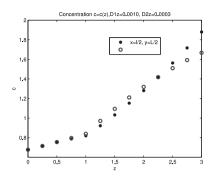


Figure 13. c depending on z for Fe in 2-layers.

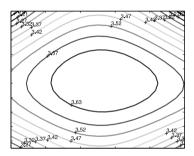


Figure 15. Levels of c by z = 2.5 for Ca in 2-layers.

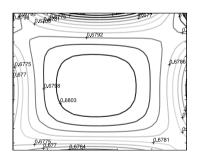


Figure 17. Levels of c by z = 0 for Fe in 2-layers.

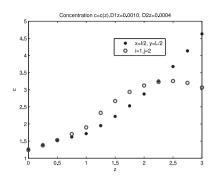


Figure 14. c depending on z for Ca in 2-layers.

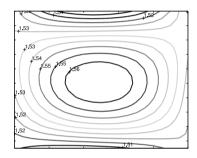


Figure 16. Levels of c by z = 2.5 for Fe in 2-layers.

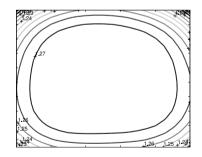
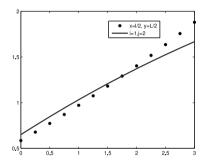


Figure 18. Levels of c by z = 0 for Ca in 2-layers.

and numerical (c_{num}) results by x = 0.5m, y = 0.5m depending on z are obtained in Table 5.

z	$c_{num} - Fe$	$c_{exp} - Fe$	$c_{num} - Ca$	$c_{exp} - Ca$
0.000	0.681	0.660	1.274	1.300
0.250	0.718		1.399	
0.500	0.753		1.515	
0.750	0.787		1.622	
1.000	0.819	0.830	1.720	1.900
1.250	0.922		1.953	
1.500	1.033		2.223	
1.750	1.153	1.150	2.530	1.980
2.000	1.281		2.875	
2.250	1.418		3.257	
2.500	1.563	1.500	3.677	2.380
2.750	1.717		4.135	
3.000	1.880	1.880	4.630	4.630

Table 5. The experimental and numerical results by x = 0.5m, y = 0.5m depending on z.



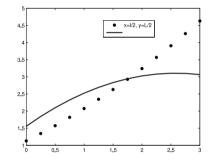


Figure 19. c depending on z for Fe in 1-layer.

Figure 20. c depending on z for Ca in 1-layer.

7.3 1 layer

For one layer we use $Z = H_1 = 3m$ and following diffusion coefficients in the layers: for Fe $D_{1z} = 10^{-3}$, and for Ca also $D_{1z} = 10^{-3}$.

The diffusion coefficients in x, y directions are $D_{1x} = D_{1y} = 310^{-4}$.

In Figs. 19, 20 are the graphics of metals concentration c depending on vertical coordinate z by x = l/2, y = L/2 and in other point. In Figs. 21–24 we can see the distribution of concentration c for Fe and for Ca in the (x, y) plane by z = 0, z = 2.5. For the peat block corresponding experimental (c_{exp}) and numerical (c_{num}) results by x = 0.5m, y = 0.5m depending on z are obtained in Table 6.

8 Conclusions

The profile of the concentration changes for metals at first may be influenced their biogenic recycling and low mobility of these elements considering also changes of water table.

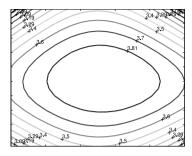


Figure 21. Levels of c by z = 2.5 for Ca in 1-layer.

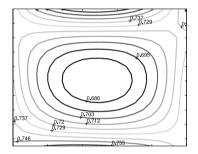


Figure 23. Levels of c by z = 0 for Fe in 1-layer.

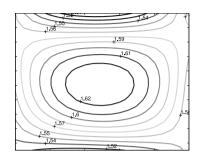


Figure 22. Levels of c by z = 2.5 for Fe in 1-layer.

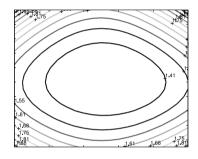


Figure 24. Levels of c by z = 0 for Ca in 1-layer.

Table 6. The experimental and numerical results by x = 0.5m, y = 0.5m depending on z.

z	$c_{num} - Fe$	$c_{exp} - Fe$	$c_{num} - Ca$	$c_{exp} - Ca$
0.000	0.586	0.660	1.131	1.300
0.250	0.678		1.346	
0.500	0.773		1.575	
0.750	0.871		1.818	
1.000	0.971	0.830	2.075	1.900
1.250	1.075		2.346	
1.500	1.182		2.631	
1.750	1.291	1.150	2.929	1.980
2.000	1.403		3.242	
2.250	1.518		3.568	
2.500	1.636	1.500	3.908	2.380
2.750	1.756		4.2621	
3.000	1.880	1.880	4.630	4.630

Changes of concentrations of studied elements in all points have similar characters - concentrations very fast decreases with depth increasing. The

major concentrations of heavy metals are observed at the top layers of peat. Concentrations of Ca and Fe very fast decreases with depth increasing. Elements concentration in peat profiles approves with respect to the possibility of using trace elements concentration as indicator of the region and global environmental pollution. The 3D diffusion problem in N layered domain described by a boundary value problem of the system of PDEs with piece-wise constant diffusion coefficients are approximate on the 2D boundary value problem of a system of N PDEs. This algorithm is used for solving the problem of metal concentration in the 3, 2 and 1 layered peat blocks. The compared numerical results with experimental data are precisely for 3-layered system.

The total advantage and attainment of an averaged method for engineering calculations is determined from the number of grid points in every of three layers. The efficiency of this method is obtained due to simple algorithms for calculations of circulant matrix. Test samples with an analytical solution (the indicator of transfer process) were developed and a numerical experiment was used to test and analyze the established method for three layers in comparison with the methods described previously. The analytical and numerical results were coincided with 3 decimal places and it means that mathematical model have a practical application in real determination of trace elements concentrations. As opposed to the models analyzed previously the newly established mathematical model envisages modeling mass transfer in N-layers. and the boundary conditions of the 3rd type included in the model enable the modeling of the substance flux through the boundary surface of the specified area in the direction of Earths interior. Mathematical modelling results and experimental data differ very slightly (completely acceptable for practice) and it means that mathematical model have practical application in real determination of trace elements concentrations. The constructed mathematical model is applicable in studying transfer processes, where substance mass is transferred through boundary surfaces of the specified area, for instance, in a purification plant, purifying works etc.

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