RELIABILITY PERFORMANCE OF WIRELESS SENSOR NETWORKS FOR CIVIL INFRASTRUCTURE – PART II: PREDICTION AND VERIFICATION

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Abstract. Application studies on wireless sensor networks (WSN) are actively conducted in the construction industry. However, there are several technical limitations including signal interference caused by the characteristics of wireless sensors, reliability degradation in wireless communication and uncertainty of configuring a network topology. This may lead to a decline in reliability and performance of real-time data acquisition methods. Thus, the paper developed a model capable of predicting reliability performance of wireless signals applied to civil infrastructures. The measured and predicted values of wireless signals are compared and analyzed through a field experiment carried out in an actual bridge to verify the prediction model suggested herein. As a result of the analysis, the prediction model demonstrated a variation up to 8.4% compared with actual measurements, proving the high accuracy of the prediction model. Furthermore, the reception rate at short distances within a 5 m radius is at least 90%, showing a highly reliable reception capacity. When this is applied to monitoring systems in the construction sector, it is believed that performance and reliability of such system can be secured.

Keywords: communication reliability, wireless sensor network, prediction, path loss, civil infrastructure.

Introduction

Recently ubiquitousness, implying something that exists anywhere, anytime, is being noticed at industry sectors. In this ubiquitous era, there is great interest on automated construction systems to enhance users’ convenience and efficiency as buildings keep getting higher, larger and more complicated. Until now, the amount of logistics or manpower input has been identified manually at construction sites, and it was highly time-consuming to collect measurement data at construction sites. These have led to issues on unnecessary costs and low efficiency. Introduction of wireless communication has been accelerated to resolve such issues.

Various types of wireless communication technologies are applied to a wide range of areas. Yet, methods to accurately predict the performance of wireless communication have been limited despite the fact that reliable data collection is required at relatively large-scale areas like construction sites. This not only generates errors in measurement data and degrades reception reliability, but also reduces stability and efficiency of the network configuration. Ultimately, it may lead to direct loss in terms of system efficiency and reliability which are essential in building wireless monitoring and tracking systems for civil infrastructure such as bridges and buildings. Therefore, the paper quantitatively analyzes various failure factors that are likely to affect wireless communications at construction sites. Also, it is intended to develop and verify a prediction model capable of identifying reliability performance of 2.4 GHz wireless communication by utilizing information on obstacle types, thickness and distance between sensors.

1. Literature review

The adoption of ZigBee as WSN technology has grown in many industrial applications responding to recent trends of remote sensing and wireless monitoring. In the civil and construction engineering areas, infrastructure monitoring, such as tunnels, dams, bridges, buildings, and highways, ZigBee is being used as the main driver of wireless data collection (Kim et al. 2011; Dhivya, Heimalatha 2013; Iqbal, Yukimatsu 2011; Miao et al. 2012; Kim et al. 2008; Dibley et al. 2012). Construction asset tracking, crew monitoring, safety monitoring and equipment tracking are other examples of ZigBee technology.
in construction engineering areas (Wu et al. 2013; Yang et al. 2011; Naticchia et al. 2013; Song et al. 2007). Some other ZigBee applications for data collection and processing also include underground monitoring, environmental monitoring, industrial control and monitoring, and localization (Sung, Tsai 2011; Xu, Wu 2012; Blumenthal et al. 2007; Hwang, Yu 2012). Although WSN technologies provide many opportunities and potential in data communication due to mobility and removal of wires, research on WSN is still in early stages with limited practical standards and applicability. In this respect, some researchers have pointed out the current challenges and raised issues regarding reliability, performance, network scalability, power management and fault tolerance (Jardosh, Ranjan 2008; Capella et al. 2005; Yick et al. 2008).

Performance reliability is one of the concerns of potential users of wireless technology in civil engineering applications. Basically, customers of civil infrastructure systems expect a similar level of performance reliability to that experienced in traditional wired systems (Silva et al. 2012). In a civil engineering sense, performance reliability means that the desired data is sent to the receiver at long distances with minimal measurement errors, as well as high data quality and delivery rate (Hwang et al. 2010). On the other hand, propagation of the radio signal through air often encounters coverage loss and deterioration of the link quality (Li et al. 2008). More complications lie in the fact that different radio frequencies, transmission power, obstruction type, and interference affect RF (Radio Frequency) propagation characteristics (Yick et al. 2008). RF propagation with a path loss model in indoor or outdoor environments has been the subject of extensive research in many wireless communities. The focus of research methods has mainly been on the theoretical waveguide model, site-specific statistical approaches, ray-tracing model, numerical model using finite difference time domain, and heuristic approaches (Sarkar et al. 2003). Nevertheless, the complexity of those methodologies and research outcomes do not completely provide practical implications to civil engineers who plan to adopt wireless sensor networks. In addition, such propagation environments are classified mainly by the building type, geometry of rooms and floors, and partitions. On the other hand, the unique characteristics of individual obstructions according to materials type and thickness have not been addressed. A broad classification of obstruction details and impractical guideline of WSN performance fail to provide a clear understanding of the WSN application framework to civil engineers.

Therefore, the methodology presented in this paper (including both parts I and II) aims to provide both experimental results and a prediction model to easily identify the performance reliability of WSN in civil infrastructure applications.

2. Path loss model

The log-distance path loss model is a generalized path loss model based on the free space path model which is applied with the pass loss exponent $n$ where values can be applied depending on the environmental conditions. The following equation can be deducted (Rappaport 2002):

$$ PL(d)[dB] = PL(d_0) + 10n \log \left( \frac{d}{d_0} \right), \hspace{1cm} (1) $$

where: $PL(d)$ refers to the log-distance path loss and $d_0$ refers to the reference distance. Various values can be applied to the path loss exponent depending on the environmental settings. The path loss gets larger as the path loss exponent $n$ increases as shown in Table 1.

Table 1. Path loss exponent, $n$, according to different environments (Rappaport 2002)

<table>
<thead>
<tr>
<th>Environment</th>
<th>Path loss exponent, $n$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Free Space</td>
<td>2</td>
</tr>
<tr>
<td>Urban area cellular radio</td>
<td>2.7 to 3.5</td>
</tr>
<tr>
<td>Shadowed urban cellular radio</td>
<td>3 to 5</td>
</tr>
<tr>
<td>In building Line-Of-Sight</td>
<td>1.6 to 1.8</td>
</tr>
<tr>
<td>Obstructed in building</td>
<td>4 to 6</td>
</tr>
<tr>
<td>Obstructed in factories</td>
<td>2 to 3</td>
</tr>
</tbody>
</table>

Meanwhile, even if the distance between the transmitter and receiver is the same under the actual wireless environment, each path may have a different path loss according to the location of the receiving module and environment. However, these factors are not specifically reflected in the free space propagation model and the log-distance path loss model described above. Log-normal shadowing model is the model that reflects these factors, and it can be expressed as the following equation:

$$ PL(d)[dB] = \overline{PL}(d) + X_\sigma = \overline{PL}(d_0) + 10n \log \left( \frac{d}{d_0} \right) + X_\sigma, \hspace{1cm} (2) $$

where: $X_\sigma$ refers to the Gaussian random variable with standard deviation of $\sigma$ with average 0. Eqn (2) reflects the random shadowing effect so that a different path loss can be generated on the same distance. In other words, even though the distance between the transmitter and receiver is the same, a different path loss can be generated depending on the surrounding environment, representing the shadowing effect. Here, shadowing implies that the radio wave that is diffracted, refracted and penetrated can reach the receiver again even if the module is blocked by an obstacle that causes interference in propagation.

The Okumura model is widely used to predict wireless signals at urban environments (Okumura et al. 1968). This model is mainly used at a frequency band of 150 MHz–1920 MHz, cell radius of 1 km–100 km and base station (BS) antenna height of 30 m–1000 m. The free space propagation model of Okumura $PL_{OK}(d)$ can be represented as the following equation:
where: $A_M(f,d)$ represents the average attenuation of means for the free space, $G_{Rx}$ and $G_{Tx}$ the transmitting antenna gain and the receiving antenna gain respectively and $G_{AREA}$ the gain according to propagation environment. $G_{Rx}$ and $G_{Tx}$ consider only the effect of antenna height. Other factors such as the antenna pattern are not taken into consideration.

Currently, the most widely used path loss model is the Hata model which was based on the Okumura model (Hata 1980). Hata has performed modeling for large cities, suburban areas and open rural areas based on the Okumura’s empirical path loss model. The path loss model at city areas can be represented as shown in Eqn (4):

$$PL_{Hata,U}(d)[dB] = -10.8 + 26.16 \log(f_c) - 13.82 \log(h_{Tx}) - C_{Rx} + (44.9 - 6.55 \log(h_{Tx})) \log(d),$$

(4)

where: $f_c$ is the valid frequency at range of 150 MHz~1500 MHz, $d$ is the T-R (Transmitter and Receiver) separation distance (km), the distance between the transmitter and receiver, and $h_{Tx}$ is the height of transmitting antenna (m). $C_{Rx}$ is the correlation coefficient of the receiving antenna, and there are 2 types according to the service propagation range. $C_{Rx}$ for transmission at narrow transmitting/receiving range can be defined as shown in Eqn (5) and $C_{Rx}$ for transmission at broad transmitting/receiving range as shown in Eqn (6):

$$C_{Rx} = 0.8 + (1.1 \log(f_c) - 0.7) h_{Rx} - 1.56 \log(f_c);$$

(5)

$$C_{Rx} = \begin{cases} 
8.29((1.54 h_{Rx}))^2 - 1.1, & \text{if } f_c \leq 200 \text{ MHz} \\
3.2((11.75 h_{Rx}))^2 - 4.97, & \text{if } f_c > 200 \text{ MHz} 
\end{cases}$$

(6)

Meanwhile, the path loss model for suburban and open rural areas can be represented as $PL_{Hata,SL}(d)$ and $PL_{Hata,OL}(d)$ respectively as shown in Eqns (7) and (8). The path loss is larger at urban areas with packed obstacles than at those with fewer obstacles:

$$PL_{Hata,SL}(d)[dB] = PL_{Hata,U}(d) - 2 \left( \log \frac{f_c}{28} \right)^2 - 5.4;$$

(7)

$$PL_{Hata,OL}(d)[dB] = PL_{Hata,U}(d) - 4.78(\log f_c)^2 + 18.33 \log(f_c) - 40.97.$$  

(8)

3. **WSN prediction model for civil infrastructure**

There have been multiple studies on empirical analyses, basically in the electrical and communications sectors, to predict wireless communication just like the path loss model specified above (Sarkar et al. 2003). The referenced model is used to predict the reception performance of wireless signals at long-distance wireless communication networks by simplifying the attenuation effect of wireless signals on terrains or artificial structures. However, it is difficult to theoretically suggest the effect of attenuation taking into account the existence of obstacles at construction sites. The reason is that various types of obstacles are spread out at the site interfering with propagation, making it more complicated to identify the performance of wireless communication. Empirical analysis and quantitative prediction of wireless communications reliability under such environment may become highly-significant technical factors in improving the overall WSN system performance. Thus, this study developed a prediction performance model for wireless signals using regression analysis, based on the result of empirical experiments (refer to Part I) on the attenuation of wireless signal performance using concrete blocks and steel plates among representative construction materials. Three RSSI, LQI and PDR indexes have been adopted for the analysis (refer to Part I): RSSI (Received Signal Strength Index) is an indicator of power measurement calculated by the receiver; LQI (Link Quality Index) is an indicator to assess quality of the communication link between nodes; and PDR (Packet Delivery Rate) is defined as the ratio of the number of successfully received packets and transmitted packets.

In this paper, the path loss model is referred to as a theoretical background to formulate the empirical equations and development of the prediction model. Prediction of RSSI is based on the path loss model described as a log function. While predictions of LQI and PDR are not directly related to the path loss model, they are inferred as power functions from both the nonlinearity of the path loss model and experimental results in Part I.

3.1. **Empirical equation**

Concrete is an insulator with a dielectric constant of around 2.1–2.3 (water is 80.1 at 20 °C), so when a wireless signal penetrates concrete, some energy is reflected and the other is penetrated. Generally, the bigger the dielectric constant, more energy is reflected and absorbed and there is less radio wave penetration. In addition, even if materials have the same dielectric constant, the thicker the wireless signal, the less the radio wave penetrates. Penetration performance is likely to change depending on the homogeneity of material. Thus, reinforced concrete may have complicated patterns when it comes to radio wave penetration.

Quantitative analysis of experiments on wireless signal performance considering characteristics of concrete blocks was conducted in Part I. The concrete block used was plain with thickness ranging from 12–60 cm to obtain 3 different indexes (RSSI, LQI and PDR) per unit distance. The measured indexes per unit distance were then plotted in regression curves. The receiving patterns
by material thickness and T-R separation distance were
analyzed to be used as reference data of the prediction
model. Based on the regression curves of raw data, Ta-
ble 2 demonstrates the empirical equations of RSSI, LQI
and PDR expressed as log and power functions. Here, “a”
and “b”, used as the equation coefficients, are functions
of thickness \( t \), where the thickness and characteristics
of concrete block are taken into consideration. The calcu-
lation is explained in detail in the next section.

Table 2. Empirical equations for concrete block (x denotes T-R
separation distance)

<table>
<thead>
<tr>
<th>Thickness [m]</th>
<th>RSSI</th>
<th>LQI</th>
<th>PDR</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>( y = a \ln x + b )</td>
<td>( y = ax^b + 100 )</td>
<td>( y = ax^b + 100 )</td>
</tr>
<tr>
<td>12</td>
<td>-6.11</td>
<td>-63.35</td>
<td>-0.09</td>
</tr>
<tr>
<td>24</td>
<td>-5.75</td>
<td>-65.24</td>
<td>-0.18</td>
</tr>
<tr>
<td>36</td>
<td>-5.39</td>
<td>-67.14</td>
<td>-0.30</td>
</tr>
<tr>
<td>48</td>
<td>-5.03</td>
<td>-69.03</td>
<td>-0.43</td>
</tr>
<tr>
<td>60</td>
<td>-4.67</td>
<td>-70.93</td>
<td>-0.56</td>
</tr>
</tbody>
</table>

Steel is a conductor with wave penetration proper-
ties that are very different from that of concrete. When a
wireless signal hits a steel object, most of the electro-
magentic field energy is reflected and only very little energy
penetrates. So, if a steel plate is placed at the T-R path,
only very little energy penetrates, resulting in a dramatic
decline in received signal strength and reduction of link
coverage. Likewise, based on the regression curves of raw
data in Part I, Table 3 demonstrates the empirical equa-
tions of RSSI, LQI and PDR expressed as log and power
functions. Here, “a” and “b”, used as the equation coeffi-
cients, are functions of thickness \( t \) of steel plate.

3.2. Signal prediction model using extended regression
function (ERF)

The regression curves of the empirical equation described
in the previous section are the log function for RSSI and
power function for LQI and PDR, and each coefficient
“a” and “b” is used. Since the coefficients applied herein
represent different characteristics according the material
properties and thickness, it requires additional statistical
analyses reflected with the values per measurement in-
dex and per material. Thus, this study intends to suggest
a methodology for general users to predict approximate
RSSI, LQI and PDR values using those empirical equa-
tions. This can be easily achieved by only calculating the
coefficients based on the T-R separation distance and the
thickness and material characteristics of the obstacles in
order to build a network using wireless sensors. To do
so, an extended regression function (ERF), in which the
thickness of obstacles applied to the previously mentioned
equation is expanded, is deducted, and coefficients “a” and “b” according to the obstacle characteristics
are applied to ERF. This methodology will be helpful to
easily and efficiently predict the performance of wireless
communication without executing a time-consuming reli-
ability test for each node when building a network with
hundreds and thousands of wireless sensor nodes.

Based on measurement data from 1 concrete block
(12 m) – 5 concrete blocks (60 cm), and steel plates from 1
sheet (1 cm) – 10 sheets (10 cm), coefficients “a” and
“b” per thickness were obtained for RSSI, LQI and PDR
respectively. Thickness of the concrete block was then
extended up to 180 cm and steel plate up to 20 cm to
calculate RSSI, LQI, and PDR. The regression curves of
coefficients “a” and “b”, where thickness is the independ-
ent variable, are shown in Figure 1. Coefficients “a” and
“b” of the concrete block and steel plate for RSSI can
be expressed linearly as they get thicker, yet there is a
difference in “a” and “b” values according to the insula-
tor and conductor characteristics. On the other hand, the
regression curve of coefficients “a” and “b” for LQI and
PDR shows a decreasing power function as the material
gets thicker. A list of coefficient functions for each meas-
urement index based on the characteristics of materials is
specified in Table 4.

Based on the coefficient functions, a prediction mod-
el using ERF with different thicknesses from 12 cm up to
180 cm for concrete blocks and 1 cm to 20 cm for steel

Table 3. Empirical equations for steel plate (x denotes T-R
separation distance)

<table>
<thead>
<tr>
<th>Thickness [m]</th>
<th>RSSI</th>
<th>LQI</th>
<th>PDR</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>( y = a \ln x + b )</td>
<td>( y = ax^b + 100 )</td>
<td>( y = ax^b + 100 )</td>
</tr>
<tr>
<td>1</td>
<td>-6.11</td>
<td>-65.75</td>
<td>-0.019</td>
</tr>
<tr>
<td>2</td>
<td>-6.02</td>
<td>-66.8</td>
<td>-0.06</td>
</tr>
<tr>
<td>3</td>
<td>-5.93</td>
<td>-67.85</td>
<td>-0.12</td>
</tr>
<tr>
<td>4</td>
<td>-5.84</td>
<td>-68.9</td>
<td>-0.24</td>
</tr>
<tr>
<td>5</td>
<td>-5.75</td>
<td>-69.95</td>
<td>-0.4</td>
</tr>
<tr>
<td>6</td>
<td>-5.66</td>
<td>-71</td>
<td>-0.6</td>
</tr>
<tr>
<td>7</td>
<td>-5.57</td>
<td>-72.05</td>
<td>-1</td>
</tr>
<tr>
<td>8</td>
<td>-5.48</td>
<td>-73.1</td>
<td>-1.5</td>
</tr>
<tr>
<td>9</td>
<td>-5.39</td>
<td>-74.15</td>
<td>-2</td>
</tr>
<tr>
<td>10</td>
<td>-5.3</td>
<td>-75.2</td>
<td>-3</td>
</tr>
</tbody>
</table>

Table 4. List of coefficient functions for measurement index in each material type

<table>
<thead>
<tr>
<th>Measurement Index</th>
<th>Function ( a(t) )</th>
<th>Function ( b(t) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>RSSI</td>
<td>( 0.03t – 6.47 )</td>
<td>( -0.158t – 61.45 )</td>
</tr>
<tr>
<td>Concrete Block</td>
<td>Steel</td>
<td>-0.09t – 6.2</td>
</tr>
<tr>
<td>LQI</td>
<td>-0.08847exp(0.0314t)</td>
<td>-0.2ln(t) + 2.0458</td>
</tr>
<tr>
<td>Concrete Block</td>
<td>Steel</td>
<td>-0.001789r3.208–</td>
</tr>
<tr>
<td></td>
<td>Plate</td>
<td>0.0554</td>
</tr>
<tr>
<td>PDR</td>
<td>-5.585e–0104.866–</td>
<td>-ln(t) + 5.603</td>
</tr>
<tr>
<td>Concrete Block</td>
<td>Steel</td>
<td>-0.002809r3.229–</td>
</tr>
<tr>
<td></td>
<td>Plate</td>
<td>0.1644</td>
</tr>
</tbody>
</table>
plates is suggested, and it is shown in Figures 2 and 3. It should be considered that coefficient functions “a” and “b” used at ERF are material thickness-dependent functions, so the coefficient that corresponds to material thickness should be chosen from Table 4 to be applied to ERF. Thus, a user can easily decide the prediction model at each T-R separation distance by applying the empirical equations with the values of coefficients “a” and “b”. It is interesting to note that the reception coverage distance slightly varies according to the measurement index in the prediction model. This is because occasional packet reception at the receiver was found even under –90 dBm yet LQI and PDR values are very low. Thus, reception coverage distances of LQI and PDR become slightly shorter than that of RSSI at the regression curve equation.

4. Verification of prediction model based on case study

This section is intended to perform verification on the reliability of the prediction model by comparing and analyzing the index values measured and calculated from the representative bridges with real wireless sensors attached. To do so, the shape of the actual bridge girder, the thickness of the obstacle penetration on the T-R path and the T-R separation distance between transmitters and a receiver were calculated. Then, the measured values and predicted values of RSSI, LQI and PDR under the same conditions were compared and analyzed. In addition, measured values and predicted values were interpolated and visually represented using a contour map for verification. Figure 4 illustrates details of a concrete and steel box girder bridges. For the concrete girder bridge, the thickness of the longitudinal and lateral girder is 31 cm and 20 cm, respectively. For the steel box girder bridge, the thickness of the box web is 1 cm and flange length of the box is 238 cm.

For verification analysis: 1) 24–32 ZigBee nodes were attached to the center of longitudinal girders, transmitting the 2.4 GHz RF packet at intervals of 1 Hz to the base station (BS) node, and the RSSI, LQI and PDR at the BS were measured; 2) assuming that the same sensor nodes are attached to the girder of the same study bridge, the information on the penetration thickness of girder existing on T-R path is applied. Then, the corresponding information is inserted as an ERF variable to calculate predicted values of RSSI, LQI and PDR.
Fig. 2. Extended regression function (ERF) for concrete block

Fig. 3. Extended regression function (ERF) for steel plate
4.1. Concrete girder bridge

The first experiment was carried out at Apryang Bridge, a concrete girder bridge situated in Gyeongsangbuk-do, South Korea. As shown in Figure 5, 24 sensors were attached to the girder and RF packets were to be sent to the BS located in the center.

Figure 6 demonstrates measured and predicted values obtained for each evaluation index with the BS at center of the concrete girder bridge. In the RSSI case, both measured and predicted values show a relatively concentric circular distribution, yet when it comes to LQI and PDR, a shallower distribution toward a longitudinal direction is shown. Since the antenna of the ZigBee module is omnidirectional, a concentric circular distribution is likely if the T-R path is on a line-of-sight (LOS) without obstacles. However, varying contour map distributions may be generated depending on the distribution of obstacles at the T-R path where the signal is blocked by the girders as shown in the experiment. Moreover, if the distance from the BS is within 5 m, measured values and the predicted values of the evaluation indexes are relatively similar, yet the T-R separation distance gets longer, slightly different distribution patterns are displayed. This implies that there may be unpredictable influencing factors as the girder where wireless signals penetration gets thicker and the T-R separation distance gets longer. This may be owing to the interference of multipath or irregular reinforcement status, yet its effect may be insignificant.

Among the three evaluation indexes, the one that may have practical meaning to construction engineers is
PDR which is the ratio of packets received out of total transmitted packets. According to Figure 6(c), the contour distribution of measured and predicted values within a 5 m radius represents a PDR of 95% or higher, indicating that it is a zone where reliability is secured when building a wireless sensor network system. Although the PDR range with secured reliability may vary according to the applied areas, a zone with at least 95% reception rate is at the permissible reliability zone when considering the general monitoring level.

4.2. Steel box girder bridge

The second experiment was performed at a steel box girder bridge called Yeonho Bridge located in Daegu, South Korea. A total of 32 sensors were attached in a box, which were set for transmission to the central BS (Fig. 7).

Figure 8 demonstrates the measured and predicted values obtained for each evaluation index with the BS at center of the steel box girder bridge. In the figure, both the measured and predicted values show a relatively concentric circular distribution, displaying relatively similar distribution patterns of measured and predicted values at the same location. Similar to the experiment on the concrete bridge, when it comes to PDR, in which general wireless sensor users like construction engineers are more interested, values measured and predicted within a 5 m radius show highly reliable values of at least 90% in average. This indicates that communication reliability is superior under a 5 m T-R separation distance when applied for general monitoring of the site.

Unlike the concrete bridge results, the measured and predicted values of the steel girder bridge were slightly different. This is believed to be resulting from the uncertainty of wireless signals that show highly varying reception performance according to peripheral conditions even where static wireless communications are carried out at the same distance and location. Moreover, since 32 wireless sensor modules were installed in a steel box, it is likely that various types of multipath such as refraction and reflection exist, and such atypical distribution of measured values is caused by electromagnetic characteristics inside the steel box. Despite all this, the distribution of measurement and prediction values within a 5 m radius is very similar in the contour map.

To verify the accuracy of the prediction model, deviation of measured and predicted values at each point where a concentric circle and a straight line meets were compared and analyzed as shown in Figure 9. The performance evaluation index at the point where the concentric circle and the straight line meet is not the actual measured value but the value interpolated by the contour map representing the evaluation index value extracted from a random location. This can propose a random evaluation method on the accuracy of the actual measurement and the prediction model. Here, the thickness of obstacles refers to the actual penetration thickness considering the incident angle and the number of girders. In addition, the deviation values of measurement and prediction are represented in percentage taking into account the full range of each evaluation index. In other words, it represents the error between measured and predicted values (in percentage) at the full span of 0 dBm and –92 dBm in case of RSSI, and the error between the measured and the predicted values at full span of 100% and 0% in case of LQI and PDR.

As shown in Figure 10, average deviation values of three evaluation indexes received from each sensor arranged in the same concentric circle are marked on the left.
Fig. 9. Selection of random measurement points in each bridge (left: BS at center; and right: BS at corner)

(a) Concrete girder bridge

(b) Steel box girder bridge

Fig. 10. Variation between measurement and prediction in each radius (left: BS at center; and right: BS at corner)

(a) Concrete girder bridge

(b) Steel box girder bridge
y-axis. Also, the actual penetration thickness of obstacles placed at the T-R path is displayed on the right y-axis, with the location of the BS distinguished as center and right corner for the concrete girder and the steel box girder bridge. The average deviation of all 4 cases is 3.4% for RSSI, 7.5% for LQI and 6.5% for PDR, verifying that the accuracy of the proposed prediction model is excellent as the error of all reception performance indexes is within 8%. When analyzing the respective evaluation index, the deviation slightly decreases as the T-R radius increases in case of RSSI. This is easily acceptable when considering the RSSI curve per T-R separation distance (refer to Fig. 2a). RSSI value dramatically decreases at a short-distance zone and as the distance gets longer, it converges around –90 dBm. Thus, fluctuation of the received signal at short distances is bigger than that at longer distances.

In the case of LQI and PDR, deviation values increase as the T-R separation distance and the thickness of obstacles increase. The measured raw data of LQI and PDR gradually decrease as the T-R separation distance and the actual penetration thickness increase, and drastically increase at the long distance zone (refer to Figs 2b and 2c). Thus, the zone where LQI and PDR changes are drastic shows a bigger deviation of measurement values per unit distance. It is believed that additional environmental factors including multipath may impact the reception performance under low signal strength. There is another result to pay attention to. The average penetration thickness of a concrete girder bridge and a steel box girder bridge is 55.0 cm and 2.1 cm respectively and even though the value of actual penetration thickness of the steel box girder bridge is very small, each reception performance at both girder bridges is similar. It can be inferred that the propagation interference of steel materials is far greater than that of concrete under the same concentric radius.

Conclusions and discussion

The study proposes a model to predict the performance of wireless communication using the least possible information such as obstacles, material characteristics and thickness, and T-R separation distance. With the lab experiment results, the study suggests a prediction model applied to the extended regression function (ERF) of RSSI, LQI and PDR by type and thickness of obstacles using regression analysis method. In addition, the model was verified by comparing and analyzing measured and predicted values from actual experiments in the selected concrete and steel girder bridges.

The prediction model showed very similarly patterned distributions with the actual measurement in 3 performance indexes while demonstrating a slight difference owing to uncertainty factors such as multipath. As represented in the error analysis, the deviation between measured and the predicted values gets bigger when the T-R distance increases. However, at least 90% of PDR is shown within a 5 m radius, demonstrating high reliability. Errors of 4.4%, 7.8%, and 8.4% were deducted in RSSI, LQI, and PDR, respectively when measured and predicted values were compared. While short coverage for higher reliability is a generic limitation of low-power Zig-Bee devices, extension of network coverage can be possibly achieved by adopting a multihop network scheme for WSN applications in large-scale civil infrastructure. It was verified that the proposed prediction model is highly accurate. If the prediction model is interconnected with 3D design tools such as BIM in the near future, it is anticipated that a highly efficient and reliable network topology design can be achieved at the construction design phase taking into consideration attenuation of wireless signals.

The presented methodology and results are one of the few approaches to explore WSN performance in civil infrastructure. Therefore, analysis on WSN accuracy performance from the prediction model compared with field experiments would provide academic and practical contribution to the application of WSN bridge monitoring.

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References


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